## 2. Any revealing of identification, appeal to evaluator and /or equations written eg, 42+8 = 50, will be treated as malpractice. Important Note: 1. On compteting your answers, compulsorily draw diagonal cross lines on the remaining blank pages.

## First Semester M.Tech. Degree Examination, December 2011 Applied Mathematics

Time: 3 hrs. Max. Marks:100

Note: Answer any FIVE full questions.

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- 1 a. Define with suitable examples: i) Significant figure ii) Round off error iii) Truncation error iv) Absolute error. (10 Marks)
  - b. A parachutist of mass 68.1 kg jumps out of a stationary hot air ballon. Use  $\frac{dv}{dt} = g \left(\frac{c}{m}\right)v$  to compute velocity v prior to opening the chute. The drag coefficient is equal to 12.5 kg/s. Given that g = 9.8, v = 0 at t = 0. Apply finite divided difference scheme with a step size of 4 seconds for the calculation. (10 Marks)
- 2 a. Explain the bisection method to find the root of the equation f(x) = 0. Use it to find five approximations for  $f(x) = x^3 5x + 1 = 0$  with four decimals in each computation. (10 Marks)
  - b. Use both the Newton-Raphson and modified Newton Raphson methods to find the real root near 2 of the equation  $x^4 11x + 8 = 0$  accurate to five decimal places. (10 Marks)
- 3 a. Perform two iterations of the Bairstow method to extract a quadratic factor  $x^2 + px + q$  from the polynomial  $x^3 + x^2 x + 2 = 0$ . Use the initial approximations p = -0.9 and q = 0.9.
  - b. Find all the roots of the polynomial  $x^3 6x^2 + 11x 6 = 0$  using the Graeffe's root squaring method. (10 Marks)
- 4 a. Given the following table of values, find  $\frac{dy}{dx}$  and  $\frac{d^2y}{dx^2}$  at x = 1.1 and x = 1.6, using suitable interpolation formula. (10 Marks)

 x
 1.0
 1.1
 1.2
 1.3
 1.4
 1.5
 1.6

 y
 7.989
 8.403
 8.781
 9.129
 9.451
 9.750
 10.031

- b. Use Ramberg's method to compute  $\int_{0}^{1} \frac{dx}{1+x^{2}}$  correct to four decimal places. (10 Marks)
- 5 a. Explain the triangularisation method to solve the system of linear equations. Solve for  $x_1 + x_2 + x_3 = 1$ ,  $4x_1 + 3x_2 x_3 = 6$  and  $3x_1 + 5x_2 + 3x_3 = 4$  using the triangularisation method. (10 Marks)
  - b. Find the inverse of the matrix,

$$A = \begin{bmatrix} 2 & 1 & 1 & -2 \\ 4 & 0 & 2 & 1 \\ 3 & 2 & 2 & 0 \\ 1 & 3 & 2 & -1 \end{bmatrix}$$
 using the partition method.

Hence, solve the system of equations AX = b where  $b = \begin{bmatrix} -10 & 8 & 7 & -5 \end{bmatrix}^T$ . (10 Marks)

## 10MMD/MDE/MEA/MCM/MAR11

- Use Householder's method to reduce the matrix  $\begin{bmatrix} 1 & 3 & 4 \\ 3 & 2 & -1 \\ 4 & -1 & 1 \end{bmatrix}$  to a tridiagonal matrix.

b. Using the Jacobi method, find all the eigen values and the corresponding eigen vectors of the

$$A = \begin{pmatrix} 1 & \sqrt{2} & 2 \\ \sqrt{2} & 3 & \sqrt{2} \\ 2 & \sqrt{2} & 1 \end{pmatrix}$$
 (10 Marks)

- a. Define a linear transformation T:  $\mathbb{R}^2 \to \mathbb{R}^2$  by  $T(x) = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -x_1 \\ x_2 \end{bmatrix}$ . Find the images under T of  $u = \begin{vmatrix} 4 \\ 1 \end{vmatrix}$ ,  $v = \begin{vmatrix} 2 \\ 3 \end{vmatrix}$  and  $u + v = \begin{vmatrix} 6 \\ 4 \end{vmatrix}$ (06 Marks)
  - b. Let  $T: \mathbb{R}^n \to \mathbb{R}^m$  be a linear transformation. Then T is one-to-one if and only if the equation T(x) = 0 has only the trivial solution. (06 Marks)
  - c. If  $T: \mathbb{R}^n \to \mathbb{R}^m$  be a linear transformation, prove that,
    - T maps  $R^n$  onto  $R^m$  iff the columns of A span  $R^m$ .
    - T is 1-1 iff the columns of A are linearly independent. (ii (08 Marks)
- 8 a. Let  $y = \begin{bmatrix} 7 \\ 6 \end{bmatrix}$  and  $u = \begin{bmatrix} 4 \\ 2 \end{bmatrix}$ . Find the orthogonal projection of y onto u. Then write y as the sum of two orthogonal vectors, one in span {u} and one orthogonal to u. (08 Marks)
  - b. Let W = span{x<sub>1</sub>, x<sub>2</sub>}, where  $x_1 = \begin{bmatrix} 3 \\ 6 \\ 0 \end{bmatrix}$  and  $x_2 = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$ . Construct an orthogonal basis {v<sub>1</sub>, v<sub>2</sub>} for W.
  - Find a least squares solution of the system Ax = b for  $A = \begin{bmatrix} 4 & 0 \\ 0 & 2 \\ 1 & 1 \end{bmatrix}$  and  $b = \begin{bmatrix} 2 \\ 0 \\ 11 \end{bmatrix}$ . (08 Marks)